

SCRITTO 9/1/2024
SOLUZIONE

Domande a risposta multipla

1. e $\frac{1+i}{3-2i} = \frac{(1+i) \cdot (3+2i)}{(3-2i) \cdot (3+2i)} = \frac{1+5i}{13}$

2. a $\left(\frac{\sqrt{3}}{2} + \frac{1}{2}i\right)^{13} = \left(\cos\left(\frac{\pi}{6}\right) + i \sin\left(\frac{\pi}{6}\right)\right)^{13} =$
 $= \cos\left(\frac{13}{6}\pi\right) + i \sin\left(\frac{13}{6}\pi\right) =$
 $= \cos\left(2\pi + \frac{\pi}{6}\right) + i \sin\left(2\pi + \frac{\pi}{6}\right) = \cos\left(\frac{\pi}{6}\right) + i \sin\left(\frac{\pi}{6}\right)$
 $= \frac{\sqrt{3}}{2} + \frac{1}{2}i$

3. (c)

4. (c)

$$(A|b) = \left(\begin{array}{ccc|c} 1 & 1 & 0 & 1 \\ 0 & 2 & 3 & 4 \\ 0 & 0 & a^3-1 & 1 \end{array} \right)$$

$\Rightarrow$ SL compatibile se e solo se $a^3 - 1 \neq 0$,
cioè $\forall a \neq 1, -\frac{1}{2} \pm i\frac{\sqrt{3}}{2}$

5. (a)

$U \cap W = \{0\}$ perché $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \notin \text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \right)$

6. (c)

$$A^{-1} = \frac{1}{\det A} \text{cof}(A) = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}$$

7. (e)

Dal teorema della dimensione abbiamo
che $2 = \dim(\mathbb{R}^2) = \dim(\ker(f)) + \text{rg}(f)$

$$\Rightarrow \text{rg}(f) \leq 2 < 3.$$

8. (e) $M_{\mathcal{B}}^{\mathcal{B}}(f) = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$ non è simmetrica.

9. (e) A simmetrica $\Rightarrow A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$

$$P_A(t) = \det \begin{pmatrix} a-t & b \\ b & c-t \end{pmatrix} = t^2 - t(a+c) + ac - b^2$$

Se $a=1, c=-1, b=i \Rightarrow \text{Sp}(A) = \{0, i\}, m_a(0)=2, m_g(0)=1$
 $\Rightarrow$ tale A non è diagonalizzabile.

10. (a)

$$\text{Giacitura di } \mathbb{H} = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mid \begin{array}{l} 2x - y + z = 0 \\ x + y + z = 0 \end{array} \right\} =$$
$$= \text{Span} \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}$$

$$\begin{cases} -3y - z = 0 \\ x + y + z = 0 \end{cases}$$

$$\text{Giacitura di } \mathbb{P} = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mid 3x + 2z = 0 \right\}$$

Si vede che $\begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}$ soddisfa l'equazione
 $3x + 2z = 0 \Rightarrow \mathbb{H}$ e $\mathbb{P}$ sono paralleli.

Esercizi

1. a) Risolviamo il SLO per trovare

una base di U :

$$\begin{cases} x_1 + x_2 + x_4 = 0 \\ 2x_1 - x_2 - x_3 = 0 \\ x_2 + x_4 = 0 \end{cases}$$

$$\xrightarrow{OE3} \begin{cases} x_1 + x_2 + x_4 = 0 \\ -3x_2 - x_3 - 2x_4 = 0 \\ x_2 + x_4 = 0 \end{cases}$$

$$\xrightarrow{OE1} \begin{cases} x_1 + x_2 + x_4 = 0 \\ x_2 + x_4 = 0 \\ -3x_2 - x_3 - 2x_4 = 0 \end{cases}$$

$$\xrightarrow{OE3} \begin{cases} x_1 + x_2 + x_4 = 0 \\ x_2 + x_4 = 0 \\ -x_3 + x_4 = 0 \end{cases}$$

$$\Rightarrow U = \text{Span} \begin{pmatrix} 0 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \dim(U) = 1.$$

$$V = \text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right). \quad \underline{\text{OSS:}} \quad v_1, v_2 \text{ l.i.} \\ \Rightarrow \dim(V) = 2.$$

$$U + V = \text{Span} \left(\begin{pmatrix} 0 \\ -1 \\ 1 \\ 1 \end{pmatrix} \overset{\in V}{}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right) =$$

$$= \text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right) = V$$

$$\Rightarrow U \cap V = U, \quad U + V = V \\ \dim(U \cap V) = 1, \text{ base di } U \cap V: \left\{ \begin{pmatrix} 0 \\ -1 \\ 1 \\ 1 \end{pmatrix} \right\},$$

$$\dim(U+V) = 2, \text{ base di } U+V: \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right\}.$$

e) Aggiungiamo alla base trovata di $U+V$ i primi due vettori della base canonica

$$\text{rg} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & -1 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix} = 4$$

$$\Rightarrow \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\} \text{ è base di } \mathbb{R}^4.$$

(c) $U \cup V = V$ in questi casi
 $\Rightarrow$ è un sottospazio vettoriale.

$$2. (a) \quad e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow f(e_1) = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad f(e_2) = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad f(e_3) = -\frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} \Rightarrow M_{\mathcal{B}}^{\mathcal{B}}(f) = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(e) \quad M_e^e(f) \text{ è a scala, } \operatorname{rg}(M_e^e(f)) = 2$$

$$\Rightarrow \operatorname{rg}(f) = 2$$

$$\operatorname{im}(f) = \operatorname{Span}(f(e_1), f(e_2)) = (e_1, e_2)$$

$$\Rightarrow \{e_1, e_2\} \text{ è base di } \operatorname{im}(f)$$

$$\dim \operatorname{Ker}(f) = 3 - 2 \quad (\text{teorema della dimensio-})$$

$$\operatorname{Ker}(f) = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 \mid \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\} = \operatorname{Span} \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

$$\Rightarrow \left\{ \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} \right\} \text{ è base di } \operatorname{Ker}(f).$$

$$(c) P_f(t) = \det \begin{pmatrix} 1-t & 0 & 3 \\ 0 & 1-t & 1 \\ 0 & 0 & -t \end{pmatrix} = (1-t)^2 \cdot (-t)$$

$$\Rightarrow Sp(f) = \{1, 0\} \quad m_a(1) = 2, m_a(0) = 1.$$

$$\Rightarrow m_g(0) = 1.$$

$$m_g(1) = 3 - \operatorname{rg} \begin{pmatrix} 0 & 0 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{pmatrix} = 2 = m_a(1)$$

$\Rightarrow f$ è diagonalizzabile.

$$V_1 = \operatorname{Span}(e_1, e_2), \quad V_0 = \operatorname{Span} \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

$\Rightarrow \{e_1, e_2, \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}\}$ è una base di $\mathbb{R}^3$ che diagonalizza f .