

Esempio HMM CpG: Forward, Backward e Posteriori (prime 3 posizioni)

Modello HMM (Isole CpG) visto durante il corso di Genomica Computazionale, Corso di Laurea Specialistica in Genomica Funzionale, 2025-2026.

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Stati nascosti: nonCpG, CpG

Transizioni:

$$P(\text{nonCpG} \rightarrow \text{nonCpG}) = 0.9, \quad P(\text{nonCpG} \rightarrow \text{CpG}) = 0.1$$

$$P(\text{CpG} \rightarrow \text{nonCpG}) = 0.5, \quad P(\text{CpG} \rightarrow \text{CpG}) = 0.5$$

Emissioni:

$$P(\text{AT} | \text{nonCpG}) = 0.98, \quad P(\text{CG} | \text{nonCpG}) = 0.02$$

$$P(\text{AT} | \text{CpG}) = 0.20, \quad P(\text{CG} | \text{CpG}) = 0.80$$

Probabilità iniziali: $\pi(\text{nonCpG}) = \pi(\text{CpG}) = 0.5$

Sequenza osservata (prime 3 posizioni): AT, AT, CG

(La sequenza completa usata per i backward è: AT AT CG CG CG AT AT AT CG AT AT.)

Forward α (prime 3 posizioni)

Definizione: $\alpha_t(s) = P(o_1, \dots, o_t, z_t = s)$

Ricorrenza: $\alpha_t(s) = P(o_t | z_t = s) \times \sum_{s'} \alpha_{t-1}(s') \cdot P(z_t = s | z_{t-1} = s')$

Posizione $t = 1$ (osservazione AT)

$$\begin{aligned} \alpha_1(\text{nonCpG}) &= \pi(\text{nonCpG}) \cdot P(\text{AT} | \text{nonCpG}) \\ &= 0.5 \cdot 0.98 \\ &= 0.49 \end{aligned}$$

$$\begin{aligned} \alpha_1(\text{CpG}) &= \pi(\text{CpG}) \cdot P(\text{AT} | \text{CpG}) \\ &= 0.5 \cdot 0.20 \\ &= 0.10 \end{aligned}$$

Posizione $t = 2$ (osservazione AT)

$$\begin{aligned} \alpha_2(\text{nonCpG}) &= P(\text{AT} | \text{nonCpG}) \times [\alpha_1(\text{nonCpG}) \cdot P(\text{nonCpG} \rightarrow \text{nonCpG}) \\ &\quad + \alpha_1(\text{CpG}) \cdot P(\text{CpG} \rightarrow \text{nonCpG})] \\ &= 0.98 \times [0.49 \cdot 0.9 + 0.10 \cdot 0.5] \\ &= 0.98 \times [0.441 + 0.05] \\ &= 0.98 \times 0.491 \\ &\approx 0.48118 \end{aligned}$$

$$\begin{aligned} \alpha_2(\text{CpG}) &= P(\text{AT} | \text{CpG}) \times [\alpha_1(\text{nonCpG}) \cdot P(\text{nonCpG} \rightarrow \text{CpG}) \\ &\quad + \alpha_1(\text{CpG}) \cdot P(\text{CpG} \rightarrow \text{CpG})] \end{aligned}$$

$$\begin{aligned}
&= 0.20 \times [0.49 \cdot 0.1 + 0.10 \cdot 0.5] \\
&= 0.20 \times [0.049 + 0.05] \\
&= 0.20 \times 0.099 \\
&= 0.0198
\end{aligned}$$

Posizione t = 3 (osservazione CG)

$$\begin{aligned}
\alpha_3(\text{nonCpG}) &= P(\text{CG}|\text{nonCpG}) \times [\alpha_2(\text{nonCpG}) \cdot P(\text{nonCpG} \rightarrow \text{nonCpG}) \\
&\quad + \alpha_2(\text{CpG}) \cdot P(\text{CpG} \rightarrow \text{nonCpG})] \\
&= 0.02 \times [0.48118 \cdot 0.9 + 0.0198 \cdot 0.5] \\
&= 0.02 \times [0.433062 + 0.0099] \\
&= 0.02 \times 0.442962 \\
&\approx 0.00885924
\end{aligned}$$

$$\begin{aligned}
\alpha_3(\text{CpG}) &= P(\text{CG}|\text{CpG}) \times [\alpha_2(\text{nonCpG}) \cdot P(\text{nonCpG} \rightarrow \text{CpG}) \\
&\quad + \alpha_2(\text{CpG}) \cdot P(\text{CpG} \rightarrow \text{CpG})] \\
&= 0.80 \times [0.48118 \cdot 0.1 + 0.0198 \cdot 0.5] \\
&= 0.80 \times [0.048118 + 0.0099] \\
&= 0.80 \times 0.058018 \\
&\approx 0.0464144
\end{aligned}$$

Backward β (posizioni t = 3,2,1)

Definizione: $\beta_t(s) = P(o_{t+1}, \dots, o_T | z_t = s)$

Ricorrenza: $\beta_t(j) = \sum_k P(z_{t+1}=k | z_t=j) \cdot P(o_{t+1}|k) \cdot \beta_{t+1}(k)$

Qui mostriamo i calcoli per t=3,2,1 (usando la sequenza completa).

Dalla sequenza completa si ottiene (calcolato una volta con la ricorrenza backward):

$$\beta_4(\text{nonCpG}) \approx 0.00284896$$

$$\beta_4(\text{CpG}) \approx 0.01087190$$

Posizione t = 3 (β_3 , osservazione successiva = CG a t=4)

$$\begin{aligned}
\beta_3(\text{nonCpG}) &= P(\text{nonCpG} \rightarrow \text{nonCpG}) \cdot P(\text{CG}|\text{nonCpG}) \cdot \beta_4(\text{nonCpG}) \\
&\quad + P(\text{nonCpG} \rightarrow \text{CpG}) \cdot P(\text{CG}|\text{CpG}) \cdot \beta_4(\text{CpG}) \\
&= 0.9 \cdot 0.02 \cdot 0.00284896 + 0.1 \cdot 0.80 \cdot 0.01087190 \\
&\approx 0.0000513 + 0.0008698 \\
&\approx 0.0009210
\end{aligned}$$

$$\begin{aligned}
\beta_3(\text{CpG}) &= P(\text{CpG} \rightarrow \text{nonCpG}) \cdot P(\text{CG}|\text{nonCpG}) \cdot \beta_4(\text{nonCpG}) \\
&\quad + P(\text{CpG} \rightarrow \text{CpG}) \cdot P(\text{CG}|\text{CpG}) \cdot \beta_4(\text{CpG}) \\
&= 0.5 \cdot 0.02 \cdot 0.00284896 + 0.5 \cdot 0.80 \cdot 0.01087190 \\
&\approx 0.0000285 + 0.0043488
\end{aligned}$$

$$\approx 0.0043773$$

Posizione t = 2 (β_2 , osservazione successiva = CG a t=3)

$$\begin{aligned}\beta_2(\text{nonCpG}) &= P(\text{nonCpG} \rightarrow \text{nonCpG}) \cdot P(\text{CG} | \text{nonCpG}) \cdot \beta_3(\text{nonCpG}) \\ &\quad + P(\text{nonCpG} \rightarrow \text{CpG}) \cdot P(\text{CG} | \text{CpG}) \cdot \beta_3(\text{CpG}) \\ &= 0.9 \cdot 0.02 \cdot 0.0009210 + 0.1 \cdot 0.80 \cdot 0.0043773 \\ &\approx 0.0000166 + 0.0003501 \\ &\approx 0.0003668\end{aligned}$$

$$\begin{aligned}\beta_2(\text{CpG}) &= P(\text{CpG} \rightarrow \text{nonCpG}) \cdot P(\text{CG} | \text{nonCpG}) \cdot \beta_3(\text{nonCpG}) \\ &\quad + P(\text{CpG} \rightarrow \text{CpG}) \cdot P(\text{CG} | \text{CpG}) \cdot \beta_3(\text{CpG}) \\ &= 0.5 \cdot 0.02 \cdot 0.0009210 + 0.5 \cdot 0.80 \cdot 0.0043773 \\ &\approx 0.0000092 + 0.0017509 \\ &\approx 0.0017601\end{aligned}$$

Posizione t = 1 (β_1 , osservazione successiva = AT a t=2)

$$\begin{aligned}\beta_1(\text{nonCpG}) &= P(\text{nonCpG} \rightarrow \text{nonCpG}) \cdot P(\text{AT} | \text{nonCpG}) \cdot \beta_2(\text{nonCpG}) \\ &\quad + P(\text{nonCpG} \rightarrow \text{CpG}) \cdot P(\text{AT} | \text{CpG}) \cdot \beta_2(\text{CpG}) \\ &= 0.9 \cdot 0.98 \cdot 0.0003668 + 0.1 \cdot 0.20 \cdot 0.0017601 \\ &\approx 0.000324 + 0.0000352 \\ &\approx 0.000359\end{aligned}$$

$$\begin{aligned}\beta_1(\text{CpG}) &= P(\text{CpG} \rightarrow \text{nonCpG}) \cdot P(\text{AT} | \text{nonCpG}) \cdot \beta_2(\text{nonCpG}) \\ &\quad + P(\text{CpG} \rightarrow \text{CpG}) \cdot P(\text{AT} | \text{CpG}) \cdot \beta_2(\text{CpG}) \\ &= 0.5 \cdot 0.98 \cdot 0.0003668 + 0.5 \cdot 0.20 \cdot 0.0017601 \\ &\approx 0.0001797 + 0.0001760 \\ &\approx 0.0003557\end{aligned}$$

Posteriori $\gamma_1, \gamma_2, \gamma_3$

Definizione generale: $\gamma_t(s) = P(z_t = s | O) = \alpha_t(s) \cdot \beta_t(s) / P(O)$
dove $P(O) = \alpha_T(\text{nonCpG}) + \alpha_T(\text{CpG}) \approx 2.11327 \times 10^{-4}$.

t = 1

$$\begin{aligned}\gamma_1(\text{nonCpG}) &= \alpha_1(\text{nonCpG}) \cdot \beta_1(\text{nonCpG}) / P(O) \\ &\approx (0.49 \cdot 0.000359) / 2.11327 \times 10^{-4} \\ &\approx 0.8317\end{aligned}$$

$$\begin{aligned}\gamma_1(\text{CpG}) &= \alpha_1(\text{CpG}) \cdot \beta_1(\text{CpG}) / P(O) \\ &\approx (0.10 \cdot 0.0003557) / 2.11327 \times 10^{-4}\end{aligned}$$

$$\approx 0.1683$$

t = 2

$$\begin{aligned}\gamma_2(\text{nonCpG}) &= \alpha_2(\text{nonCpG}) \cdot \beta_2(\text{nonCpG}) / P(O) \\ &\approx (0.48118 \cdot 0.0003668) / 2.11327 \times 10^{-4} \\ &\approx 0.8351\end{aligned}$$

$$\begin{aligned}\gamma_2(\text{CpG}) &= \alpha_2(\text{CpG}) \cdot \beta_2(\text{CpG}) / P(O) \\ &\approx (0.0198 \cdot 0.0017601) / 2.11327 \times 10^{-4} \\ &\approx 0.1649\end{aligned}$$

t = 3

$$\begin{aligned}\gamma_3(\text{nonCpG}) &= \alpha_3(\text{nonCpG}) \cdot \beta_3(\text{nonCpG}) / P(O) \\ &\approx (0.00885924 \cdot 0.0009210) / 2.11327 \times 10^{-4} \\ &\approx 0.0386\end{aligned}$$

$$\begin{aligned}\gamma_3(\text{CpG}) &= \alpha_3(\text{CpG}) \cdot \beta_3(\text{CpG}) / P(O) \\ &\approx (0.0464144 \cdot 0.0043773) / 2.11327 \times 10^{-4} \\ &\approx 0.9614\end{aligned}$$

Si vede che alle posizioni 1 e 2 (AT) la probabilità a posteriori di nonCpG è alta (~83–84%), mentre alla posizione 3 (CG) la probabilità di CpG è molto alta (~96%), in corrispondenza dell'osservazione di una potenziale CpG.