

- 1) Consider the example of Lifetime utility maximization.
Solve it assuming $U(C) = \ln C$, $r = 1$, $\delta = 0$, $K(0) = 1$ and $T = 1$.

$$\begin{aligned} & \max \int_0^1 \ln C(t) dt \\ & \text{subject to} \\ & K' = K(t) - C(t) \\ & K(0) = 1 \quad K(1) \geq 0 \end{aligned}$$

The Hamiltonian function is

$$H = \ln C(t) + \lambda(K(t) - C(t))$$

- (i) $\frac{dH}{dC} = \frac{1}{C(t)} - \lambda = 0$
(ii) $K' = K(t) - C(t)$
(iii) $\lambda' = -\lambda$
(iv) $\lambda(1) \geq 0, K(1) \geq 0, (K(1))\lambda(1) = 0$
(Truncated vertical line)

Solving (iii) we get $\lambda(t) = \lambda_0 e^{-t}$ where λ_0 is an arbitrary constant
(note that (iii) is an homogeneous differential equation with constant term and constant coefficient)

Replacing in (i) $\frac{1}{C(t)} = \lambda_0 e^{-t} \rightarrow C(t) = \lambda_0^{-1} e^t$

Then $C(t)$ is increasing in t if $\lambda_0 > 0$

Replacing in (ii) we get:

$$K' - K(t) = -\lambda_0^{-1} e^t$$

(note the general form of a first order linear differential equation is $\frac{dy}{dt} + u(t)y = w(t)$)

The general solution of this differential equation is given by

$$K(t) = e^{-\int u(t)dt} (A + \int w(t)e^{\int u(t)dt} dt)$$

where $u(t) = -1$, $w(t) = -\lambda_0^{-1} e^t$ and $\int u(t)dt = -\int 1 dt = -t - k$ where k is an arbitrary constant. Replacing into the expression above we have:

$$\begin{aligned} K &= e^{t+k} (A - \lambda_0^{-1} \int e^{-k} dt) \\ K(t) &= e^{t+k} (A - \lambda_0^{-1} e^{-k} (t+h)) \quad \text{where } h \text{ is an arbitrary constant} \end{aligned}$$

$$K(t) = (Ae^{t+k} - \lambda_0^{-1} e^t (t+h))$$

Note that:

- 1) Given that $C(t) = \lambda_0^{-1} e^t$, λ_0 must be different from 0 otherwise $C(t)$ is not defined
 - 2) given that $\lambda(t) = \lambda_0 e^{-t}$ for any $\lambda_0 \neq 0$ we have that for $t = 1 \rightarrow \lambda(1) = \lambda_0 e^{-1} \neq 0$
- Then the terminal condition has to be $K(1) = 0$
Using the initial and the terminal conditions:

$$K(0) = (Ae^k - \lambda_0^{-1} h) = 1$$

$$K(1) = e \left(Ae^k - \lambda_0^{-1}(1+h) \right) = 0$$

From the second equation we have $Ae^k = \lambda_0^{-1}(1+h)$ and replacing in the first one:

$$\lambda_0^{-1}((1+h) - h) = 1 \rightarrow \lambda_0 = 1$$

Replacing $\lambda_0 = 1$ in $K(t)$ we have:

$$K(t) = \left(Ae^{t+k} - e^t(t+h) \right) = e^t(Ae^k - t - h) = e^t(B - t)$$

where B is an arbitrary constant. Using Initial and terminal conditions we find that $B = 1$, then:

$$K(t) = e^t(1 - t)$$

Replacing $\lambda_0 = 1$ in $C(t)$ the optimal consumption path:

$$C(t) = e^t$$

Replacing $\lambda_0 = 1$ in $\lambda(t)$ we get the evolution of the shadow prices

$$\lambda(t) = e^{-t}$$

2) Consider the problem above in discrete time.

a. Solve it with $T = 4$. (the function to maximize is $\sum_{t=0}^4 U(C_t)$)

The problem is:

$$\begin{aligned} \max_{C_t} \quad & \sum_{t=0}^4 \ln C_t \\ \text{s. t.} \quad & C_t = 2K_t - K_{t+1} \\ & K_0 = 1 \end{aligned}$$

Note that:

- i) $\delta = 0$ in continuous time is equivalent to a discount factor equal 1 in discrete time.
- ii) the constraint $K' = K(t) - C(t)$ in discrete time becomes

$$K_{t+1} - K_t = K_t - C_t$$
- iii) in the solution $K_5 = 0$ (no residual capital is left because utility function satisfies no satiation)

Replacing the constraint into the objective function:

$$\begin{aligned} \max_{K_t} \quad & \sum_{t=0}^4 \ln(2K_t - K_{t+1}) \\ & 0 \leq K_{t+1} \leq 2K_t \\ & K_0 = 1 \end{aligned}$$

The first order condition is

$$\begin{aligned} -\frac{1}{2K_{t-1} - K_t} + \frac{2}{2K_t - K_{t+1}} &= 0 \\ -\frac{1}{C_{t-1}} + \frac{2}{C_t} &= 0 \end{aligned}$$

that gives

$$C_t = 2C_{t-1}$$

We can explicit each C_t as

$$C_t = 2^t C_0.$$

$$\begin{aligned} x_0 = 1 &= \sum_{t=0}^4 \frac{c_t}{R^{t+1}} = \sum_{t=0}^4 \frac{2^t C_0}{2^{t+1}} = \sum_{t=0}^4 \frac{C_0}{2} \\ C_0 &= \frac{2}{5} \\ C_t &= \frac{2^{t+1}}{5} \end{aligned}$$

b. Solve it with $T = \infty$.

The reduced problem now is

$$\begin{aligned} \max_{K_t} \sum_{t=0}^{\infty} \ln(2K_t - K_{t+1}) \\ 0 \leq K_{t+1} \leq 2K_t \\ K_0 = 1 \end{aligned}$$

The first order condition is

$$\begin{aligned} -\frac{1}{2K_{t-1} - K_t} + \frac{2}{2K_t - K_{t+1}} = 0 \\ -\frac{1}{C_{t-1}} + \frac{2}{C_t} = 0 \end{aligned}$$

that gives

$$C_t = 2C_{t-1}$$

We can explicit each C_t as

$$C_t = 2^t C_0.$$

$$x_0 = 1 = \sum_{t=0}^{\infty} \frac{c_t}{R^{t+1}} = \sum_{t=0}^{\infty} \frac{2^t C_0}{2^{t+1}} = \sum_{t=0}^{\infty} \frac{C_0}{2}$$

Cannot be satisfied for every positive value of C_0 . Then, no solution.

3) Maximize $\int_0^T \ln(q) e^{-\delta t} dt$ subject to $s' = -q$ and $S(0) = s_0, S(T) \geq 0$

$$H = \ln(q) e^{-\delta t} + \lambda(-q)$$

- (i) $\frac{dH}{dq} = \frac{1}{q} e^{-\delta t} - \lambda = 0$
- (ii) $s' = -q$
- (iii) $\lambda' = 0$
- (iv) $\lambda(T) \geq 0, s(T) \geq 0, (s(T))\lambda(T) = 0$

From (iii) $\lambda(t) = \lambda_0 \quad \forall t$ (where λ_0 is constant)

From (i) we have:

$$\frac{1}{q} e^{-\delta t} - \lambda_0 = 0 \rightarrow q = \frac{1}{\lambda_0} e^{-\delta t}$$

Replacing q in (ii) we get:

$$s' = -\frac{1}{\lambda_0} e^{-\delta t}$$

$$s = -\int \frac{1}{\lambda_0} e^{-\delta t} dt = \frac{1}{\delta \lambda_0} e^{-\delta t} + h$$

Note λ_0 has to be different from zero otherwise q and s are not defined.

Therefore condition (iv) has to be $s(T) = 0$

$$h = -\frac{1}{\delta \lambda_0} e^{-\delta T} \quad [1]$$

Using initial condition we have:

$$s_0 = \frac{1}{\delta \lambda_0} + h$$

Replacing h using [1] and solving by λ_0 we get:

$$s_0 = \frac{1}{\delta \lambda_0} (1 - e^{-\delta T})$$

$$\lambda_0 = \frac{1}{\delta s_0} (1 - e^{-\delta T})$$

Replacing λ_0 in [1] we get

$$h = -\frac{1}{\delta \lambda_0} e^{-\delta T} = \frac{e^{-\delta T}}{(1 - e^{-\delta T})} s_0$$

Replacing in the expression for s :

$$s = \frac{1}{\delta \lambda_0} e^{-\delta t} + h = \frac{e^{-\delta t}}{1 - e^{-\delta T}} s_0 + \frac{e^{-\delta T}}{1 - e^{-\delta T}} s_0 = \frac{e^{-\delta t} + e^{-\delta T}}{1 - e^{-\delta T}} s_0$$

Section 20.2

Ex. 1

$$H = 6y + \lambda(y + u)$$

Conditions are:

1. $\frac{dH}{du} = \lambda$
2. $y' = y + u$
3. $\lambda' = -6 - \lambda$
4. $\lambda(8) = 0$
5. $y(0) = 10$

The general solution of 3 is

$$\lambda(t) = Ae^{-t} - 6$$

We can use the transversality condition to find the definite solution

$$\lambda(8) = Ae^{-8} - 6 = 0$$

$$A = 6e^8$$

The definite solution is

$$\lambda(t) = 6e^{8-t} - 6$$

Then $> 0 \forall 0 \leq t \leq 8$.

By condition 1 we can say that the Hamiltonian is maximized for $u = 2 \forall 0 \leq t \leq 8$

Replacing in 2 we have

$$y' = y + 2$$

The general solution of is

$$y(t) = Ae^t - 2$$

Using the initial condition $y(0) = 10$ we find the definite solution:

$$y(0) = Ae^0 - 2 = 10$$

$$A = 12$$

That is:

$$y(t) = 12e^t - 2$$