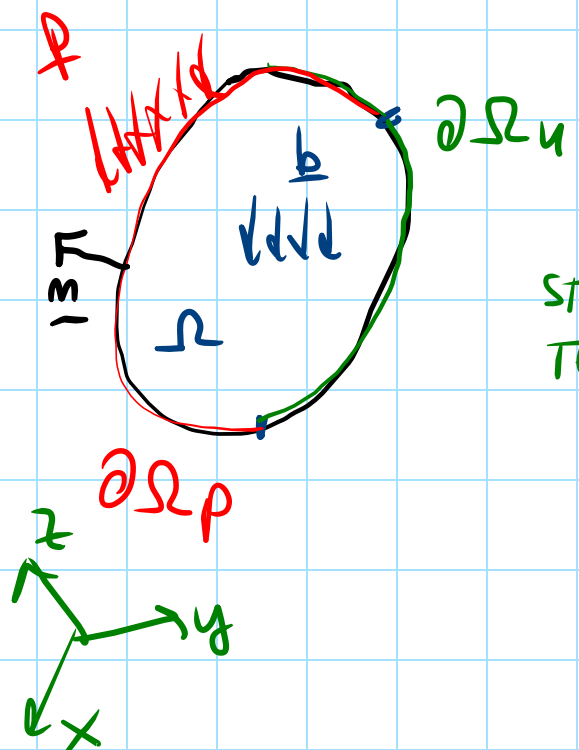


LINEAR ELASTIC PROBLEM



→ COUCHY STRESS TENSOR

$$\text{div } \underline{\underline{\sigma}} + \underline{\underline{b}} = \underline{\underline{0}} \quad (3 \text{ EQS})$$

STRAIN TENSOR

$$\underline{\underline{\epsilon}} = \frac{1}{2} (\nabla \underline{u} + \nabla \underline{u}^T) \quad (6 \text{ EQS})$$

→ DISPL. FIELD

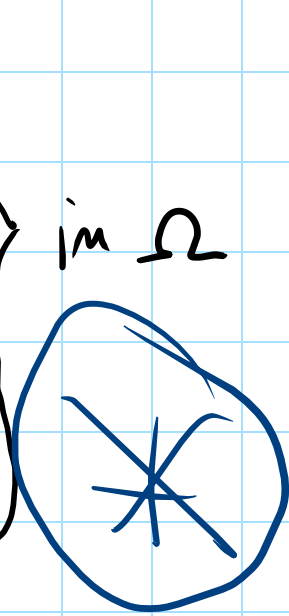
$$\underline{\underline{\sigma}} = \underline{\underline{C}} \underline{\underline{\epsilon}} \quad (6 \text{ EQS})$$

$$\underline{u} = \underline{u}^0 \quad \leftarrow \text{GIVEN}$$

$$\underline{\underline{\sigma}}_m = \underline{p}$$

in $\partial\Omega_u$

in $\partial\Omega_p$



15 EQS IN
15 UNKNOWN S

6: COMPON. OF $\underline{\underline{\sigma}}$
6: " " $\underline{\underline{\epsilon}}$
3: " " \underline{u}

$\underline{\underline{\sigma}}(x, y, z)$
 $\underline{\underline{\epsilon}}(x, y, z)$
 $\underline{u}(x, y, z)$
in Ω

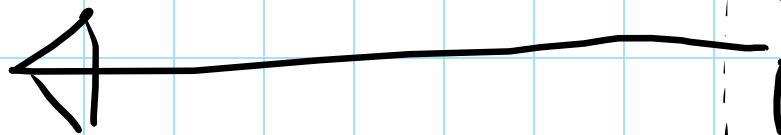
1) DISPLACEMENT FORMULATION (NAVIER)

$$\text{div} \left[\frac{1}{2} \underline{\underline{C}} (\nabla \underline{u} + \nabla \underline{u}^T) \right] + \underline{\underline{b}} = \underline{\underline{0}} \quad \text{in } \Omega$$

$$\underline{u} = \underline{u}^0 \quad \text{in } \partial\Omega_u$$

$$\left(\frac{1}{2} \underline{\underline{C}} (\nabla \underline{u} + \nabla \underline{u}^T) \right)_m = \underline{p} \quad \text{in } \partial\Omega_p$$

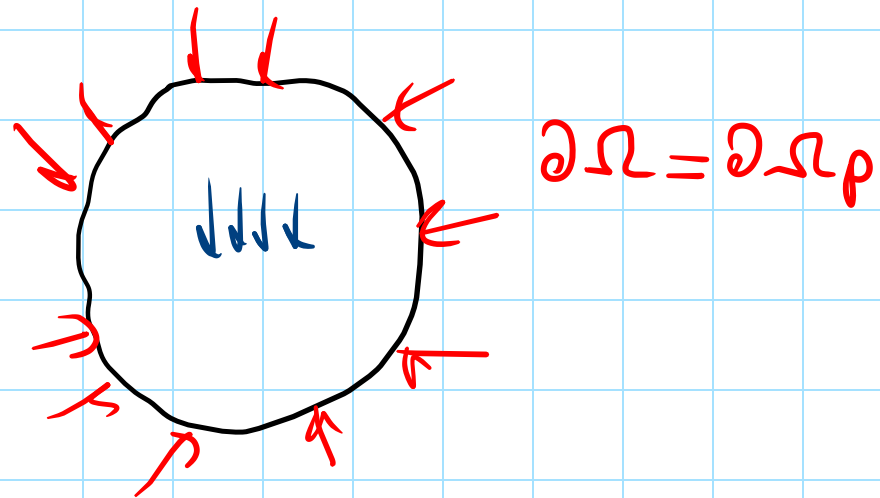
3 EQS. IN
3 UNKNOWN S $\begin{pmatrix} u_x \\ u_y \\ u_z \end{pmatrix}$



IF WE FORMULATE A F.E.M. STARTING FROM STATIONARITY OF T.P.E.
 $\Pi(\underline{u})$

2) STRESS FORMULATION (BELTRAMI - MICHELL)

IT IS POSSIBLE TO EXPRESS THE L.E.L.-PR. PRIMARILY IN TERMS OF THE 6 COMPONENTS OF STRESS $\underline{\underline{\sigma}}$. THIS FORMULATION IS NOT PARTICULARLY SUITABLE WHEN $\partial\Omega_u$ IS PRESENT. WHEN, INSTEAD, $\partial\Omega_u = \emptyset$, THIS APPROACH CAN BE EXPLOITED



THE CORRESPONDING F.E.M. IS THAT BASED ON THE COMPLEMENTARY POTENTIAL

ENERGY : $\Pi^c(\underline{\underline{\sigma}})$

$$\Pi^c(\underline{\underline{\sigma}}) = \frac{1}{2} \int_{\Omega} \underline{\underline{\sigma}} \cdot \underline{\underline{\varepsilon}} \, dV - \int_{\partial\Omega_p} \underline{p} \cdot \underline{u} \, dS - \int_{\Omega} \underline{b} \cdot \underline{u} \, dV - \int_{\partial\Omega_u} \underline{z} \cdot \underline{u}^0 \, dS$$

REACTIONS

$$= \frac{1}{2} \int_{\Omega} \underline{\underline{\sigma}} \cdot \underline{\underline{D}}^{-1} \underline{\underline{\sigma}} \, dV - \int_{\partial\Omega_p} \underline{\underline{\sigma}}_M \cdot \underline{u} \, dS \dots$$

3) MIXED FORMULATION

THE UNKNOWN ARE \underline{u} (3 COMPONENTS) AND $\underline{\underline{\sigma}}$ (6 COMPONENTS).

THIS IS VERY USEFUL FOR MIXED BOUNDARY CONDITIONS ($\partial\Omega_u, \partial\Omega_p \neq \emptyset$)

\Rightarrow THE F.E.M. ASSOCIATED IS BASED ON HEUNGER-REISSNER FUNCTIONAL

4) COMPLETE FORMULATION

ALL ITS UNKNOWN ARE PRIMARY VARIABLES.

THE FEM IS BASED ON HU-WASHIZU FUNCTIONAL

"STRONG" AND WEAK FORMULATIONS IN LINEAR ELASTICITY

THE PROBLEM SET IN ~~(*)~~ IS THE "STRONG" FORMULATION OF L-EI-PROBLEM

"WEAK" FORMULATIONS ARE THOSE BASED ON INTEGRAL EQUATIONS \Rightarrow

\Rightarrow FUNCTIONALS SUITABLY DEFINED:

EX! STAT. OF T.P.E. : $\Pi(u)$

" " COMPL. T.P.E. : $\Pi^c(\underline{\sigma})$

" " H.I.-R. : $H_R(u, \underline{\sigma})$

" " H.-W. : $H_W(u, \underline{\varepsilon}, \underline{\sigma})$

PRINCIPLE OF VIRTUAL
WORK

GALERKIN METHODS

HOW TO WRITE THE RIGHT FUNCTIONAL?

START FORM:
$$TPE = \underbrace{\frac{1}{2} \int_{\Omega} \underline{\underline{\sigma}} \cdot \underline{\underline{\varepsilon}} \, dV}_{\text{STRAIN ENERGY IN THE BODY}} - \int_{\Omega} \underline{b} \cdot \underline{u} \, dV - \int_{\partial\Omega_p} \underline{p} \cdot \underline{u} \, dS - \int_{\partial\Omega_u} \underline{q} \cdot \underline{u}^0 \, dS$$

$$\Pi(\underline{u}) = \frac{1}{2} \int_{\Omega} \frac{1}{2} \underline{\underline{\underline{C}}} (\nabla \underline{u} + \nabla \underline{u}^T) \cdot \frac{1}{2} (\nabla \underline{u} + \nabla \underline{u}^T) \, dV - \dots - \dots$$

$$HW(\underline{u}, \underline{\underline{\varepsilon}}, \underline{\underline{\sigma}}) = \frac{1}{2} \int_{\Omega} \underline{\underline{C}} \underline{\underline{\varepsilon}} \cdot \underline{\underline{\varepsilon}} \, dV - \int_{\Omega} \underline{b} \cdot \underline{u} \, dV - \int_{\partial\Omega_p} \underline{p} \cdot \underline{u} \, dS - \int_{\partial\Omega_u} \underline{\underline{\sigma}}_m (\underline{u} - \underline{u}^0) \, dS + \int_{\Omega} \underline{\underline{\sigma}} \cdot \left[\frac{1}{2} (\nabla \underline{u} + \nabla \underline{u}^T) - \underline{\underline{\varepsilon}} \right] \, dV$$

FORMALLY 0

$$HIR(\underline{u}, \underline{\underline{\sigma}}) = \frac{1}{2} \int_{\Omega} \underline{\underline{\sigma}} \cdot (\nabla \underline{u} + \nabla \underline{u}^T) \, dV - \frac{1}{2} \int_{\Omega} \underline{\underline{\sigma}} \cdot \underline{\underline{C}}^{-1} \underline{\underline{\sigma}} \, dV - \int_{\Omega} \underline{b} \cdot \underline{u} \, dV - \int_{\partial\Omega_p} \underline{p} \cdot \underline{u} \, dS - \int_{\partial\Omega_u} \underline{\underline{\sigma}}_m \cdot (\underline{u} - \underline{u}^0) \, dS$$

STRAIN ENERGY

RECALL THAT IMPOSING STATIONARITY OF THOSE FUNCTIONALS MEAN

$$\Pi(\underline{u}) \longrightarrow \delta \Pi(\underline{u}) = 0$$

$$HW(\underline{u}, \underline{\xi}, \underline{\sigma}) \longrightarrow \delta_{\underline{u}} HW = 0, \quad \delta_{\underline{\xi}} HW = 0, \quad \delta_{\underline{\sigma}} HW = 0$$

$$HR(\underline{u}, \underline{\sigma}) \longrightarrow \delta_{\underline{u}} HR = 0, \quad \delta_{\underline{\sigma}} HR = 0$$

FORMAL F.E.M. OF A LINEAR ELASTIC PROBLEM USING STAT. OF $\Gamma(u)$

DISPL. FIELD IN THE ELEMENT

ELEMENT: TET

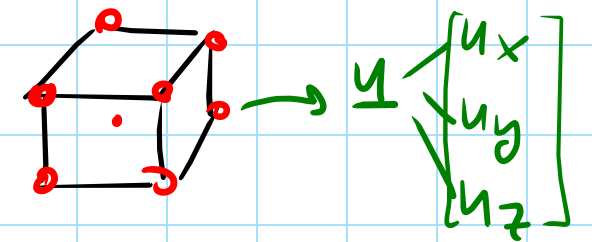
m NODES

(3) $\underline{u}(x,y,z) = \underline{N} \underline{U}_e$
 SHAPE FUNCTION \leftarrow (3x3m)

N_1 : SHAPE FUNCTION

= 1 IN NODE 1

= 0 IN THE OTHER NODES



$$\underline{N} = \begin{bmatrix} N_1 & 0 & 0 & \dots & N_m & 0 & 0 \\ 0 & N_1 & 0 & \dots & 0 & N_m & 0 \\ 0 & 0 & N_1 & \dots & 0 & 0 & N_m \end{bmatrix}$$

$$u_x(x,y,z) = N_1 u_{1x} + N_2 u_{2x} + \dots + N_m u_{mx}$$

OUR GOAL IS NOW TO OBTAIN:

(6) $\underline{\epsilon}(x,y,z) = \underline{B} \underline{U}_e$

(6x3m) (3m)

NOTE FROM DISPL \rightarrow STRAIN
 THERE IS DIFFERENTIATION

$\underline{B} = [\partial] \underline{N}$
 (6x3m) (6x3) (3x3m)

$\underline{U}_e = \begin{bmatrix} u_{1x} \\ u_{1y} \\ u_{1z} \\ \vdots \\ u_{mx} \\ u_{my} \\ u_{mz} \end{bmatrix}$ (3m)

$$[\partial] = \begin{bmatrix} \cdot, x & 0 & 0 \\ 0 & \cdot, y & 0 \\ 0 & 0 & \cdot, z \\ 0 & \frac{1}{2} \cdot, z & \frac{1}{2} \cdot, y \\ \frac{1}{2} \cdot, z & 0 & \frac{1}{2} \cdot, x \\ \frac{1}{2} \cdot, y & \frac{1}{2} \cdot, x & 0 \end{bmatrix}$$

$$\underline{\epsilon} = \begin{bmatrix} u_{x,x} & \frac{1}{2}(u_{x,y} + u_{y,x}) \\ \vdots & \vdots \\ u_{y,y} & \dots \end{bmatrix}$$

$$\underline{\underline{\varepsilon}} = \begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \\ \varepsilon_{zy} \\ \varepsilon_{xz} \\ \varepsilon_{xy} \end{bmatrix} \quad (6)$$

AFTER $\underline{\underline{\varepsilon}} = \underline{\underline{B}} \underline{U}_e \longrightarrow$

CONST. RELATIONSHIP

$$\underline{\underline{\sigma}} = \underline{\underline{C}} \underline{\underline{\varepsilon}}$$

(6) (6x6) (6)

VOIGT
NOTATION

AT THE ELEMENT LEVEL

$$\Pi(\underline{u}) = \frac{1}{2} \int_{\Omega_e} \underline{\underline{\varepsilon}} \cdot \underline{\underline{C}} \underline{\underline{\varepsilon}} dV - \int_{\Omega_e} \underline{b} \cdot \underline{u} dV = \frac{1}{2} \int_{\Omega_e} \underline{\underline{B}} \underline{U}_e \cdot \underline{\underline{C}} \underline{\underline{B}} \underline{U}_e dV - \int_{\Omega_e} \underline{b} \cdot \underline{N} \underline{U}_e dV$$

$$= \frac{1}{2} \int_{\Omega_e} \underline{U}_e \cdot \underline{\underline{B}}^T \underline{\underline{C}} \underline{\underline{B}} \underline{U}_e dV - \int_{\Omega_e} \underline{N}^T \underline{b} \cdot \underline{U}_e dV$$

$$= \underline{U}_e \cdot \left[\frac{1}{2} \int_{\Omega_e} \underline{\underline{B}}^T \underline{\underline{C}} \underline{\underline{B}} dV \right] \underline{U}_e - \underline{U}_e \cdot \left[\int_{\Omega_e} \underline{N}^T \underline{b} dV \right]$$

STIFFNESS MATRIX
OF ELEMENT $\underline{\underline{K}}_e$

VECTOR OF NODAL
FORCES \underline{F}_e

$$\Pi = \frac{1}{2} \underline{U}_e \cdot \underline{\underline{K}}_e \underline{U}_e - \underline{U}_e \cdot \underline{F}_e$$

$$\frac{\partial \Pi}{\partial \underline{U}_e} = 0 \Rightarrow \underline{\underline{K}}_e \underline{U}_e - \underline{F}_e = 0$$

CHECK DIMENSIONS OF $\underline{K}_e \sim \underline{B}^T \underline{C} \underline{B}$
 $(3m \times 3m)$ OK!

$$\underline{(3m \times 6)} \underline{(6 \times 6)} \underline{(6 \times 3m)}$$

$$\underline{F}_e \sim \underline{N}^T \underline{b}$$

$(3m)$

$$\underline{(3m \times 3)} (3)$$