

# Introduction to Curvature and other Tensors on Riemannian manifolds

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Consider, for  $X, Y, Z \in \mathcal{X}(M)$ , the map

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$R(X, Y)$  is bilinear since

$$\begin{aligned} R(X, Y)(fZ) &= f(\nabla_Y \nabla_X - \nabla_X \nabla_Y)Z + ([Y, X]f)Z + f\nabla_{[X, Y]}Z + ([X, Y]f)Z \\ &= fR(X, Y)Z \end{aligned}$$

Furthermore the following properties hold

① *Linearity in the first entry*

$$R(fX_1 + gX_2, Y) = fR(X_1, Y) + gR(X_2, Y) \text{ for any } X_1, X_2, Y \in \mathcal{X}(M) \text{ and } f, g \in \mathcal{D}(M)$$

② *Linearity in the second entry*

$$R(X, fY_1 + gY_2) = fR(X, Y_1) + gR(X, Y_2) \text{ for any } X, Y_1, Y_2 \in \mathcal{X}(M) \text{ and } f, g \in \mathcal{D}(M)$$

③ *First Bianchi identity*

$$R(X, Y)Z + R(Y, Z)X + R(Z, X)Y = 0$$

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It turns out that

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- 2  $\mathcal{R}(X, Y, Z, W) + \mathcal{R}(Y, Z, X, W) + \mathcal{R}(Z, X, Y, W) = 0$ ,  
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- 5  $\mathcal{R}(X, Y, Z, W) = \mathcal{R}(W, Z, X, Y) \forall X, Y, Z, W \in \mathcal{X}(M)$

## Definition (Sectional curvature)

Let  $S \subset T_p M$  be a two dimensional subspace of  $T_p M$  ( $M$  Riemmanian manifold). If  $x, y \in S$  are two linearly independent vectors, one can calculate

$$K_p(x, y) := \frac{\mathcal{R}(x, y, x, y)}{|x \wedge y|^2}$$

where  $|x \wedge y| = \sqrt{|x|^2|y|^2 - \langle x, y \rangle^2}$ .

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## Proposition

*The sectional curvature is independent of the choice of linearly independent vectors in  $S$ , so one can consider  $K_p(S)$ .*

## Lemma

Let  $\mathcal{V}$  be a vector space of dimension at least 2, equipped with an inner product  $\langle \cdot, \cdot \rangle$ . Let  $r, r' : \mathcal{V} \times \mathcal{V} \times \mathcal{V} \rightarrow \mathcal{V}$  be trilinear mappings which satisfy the symmetry conditions proved for  $R$  (and  $\mathcal{R}$ ) and define

$$\tau(x, y, z, w) := \langle r(x, y, z), w \rangle \quad k(\mathcal{S}) := \frac{\tau(x, y, x, y)}{|x \wedge y|^2}$$

$$\tau'(x, y, z, w) := \langle r'(x, y, z), w \rangle \quad k'(\mathcal{S}) := \frac{\tau'(x, y, x, y)}{|x \wedge y|^2} \quad \text{where } x, y \text{ are}$$

linearly independent vectors of  $\mathcal{V}$  which span the two dimensional subspace  $\mathcal{S}$  of  $\mathcal{V}$ .

If  $k(\mathcal{S}) = k'(\mathcal{S})$  for any two dimensional subspace  $\mathcal{S}$  of  $\mathcal{V}$ , then  $r = r'$  (and, equivalently,  $\tau = \tau'$ ).

# Constant sectional curvature

## Proposition

Let  $M$  be a Riemannian manifold,  $p \in M$  and  $r : T_pM \times T_pM \times T_pM \rightarrow T_pM$  be the tri-linear mapping defined by

$$\langle r(x, y, z), w \rangle = \langle x, z \rangle \cdot \langle y, w \rangle - \langle y, z \rangle \cdot \langle x, w \rangle$$

with  $x, y, z, w \in T_pM$ . Then  $M$  has constant sectional curvature  $K_0$  if and only if  $R = K_0 r$  where  $R$  is the curvature of  $M$ .

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## Proof.

If  $M$  has constant sectional curvature  $K_0$ , then for  $x, y$  linearly independent vectors in  $T_pM$

$$\mathcal{R}(x, y, x, y) = \langle R(x, y)x, y \rangle = K_0(|x \wedge y|^2) = K_0(|x|^2|y|^2 - \langle x, y \rangle^2).$$



## Proof.

On the other hand,

$$\langle r(x, y, x), y \rangle = \langle x, x \rangle \cdot \langle y, y \rangle - \langle y, x \rangle \cdot \langle x, y \rangle = |x|^2 |y|^2 - \langle x, y \rangle^2$$

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## Remark

*In coordinates, with respect to an orthonormal basis  $(e_1, \dots, e_n)$  of  $T_p M$ , it turns out that a Riemannian manifold  $M$  has constant sectional curvature if and only if*

$$R_{ijkl} = \langle R(e_i, e_j)e_k, e_l \rangle = K_0(\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk}).$$

## Remark

Since the Kronecker delta is such that  $\delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$ , it turns out that a Riemannian manifold  $M$  has constant sectional curvature if and only if  $R_{ijij} = -R_{ijji} = K_0$  for  $i \neq j$  and  $R_{ijkl} = 0$  in all the other cases.

## Definition

Let  $M$  be a Riemannian manifold,  $p \in M$ . Consider in  $T_p M$  a unit vector  $x$  and an orthogonal basis  $(e_1, \dots, e_{n-1})$  of the hyperplane in  $T_p M$  orthogonal to  $x$  and put  $x = e_n$ .

$$\begin{aligned} Ric_p(x) &:= \frac{1}{n-1} \sum_{i=1}^{n-1} \langle R(x, e_i)x, e_i \rangle = \\ &= \frac{1}{n-1} \sum_{i=1}^{n-1} \mathcal{R}(x, e_i, x, e_i) = \frac{1}{n-1} \sum_{i=1}^{n-1} \mathcal{R}(e_n, e_i, e_n, e_i) = Ric_p(e_n) \end{aligned}$$

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$$\begin{aligned} K(p) &:= \frac{1}{n(n-1)} \sum_{i,j=1}^n \langle R(e_j, e_i)e_j, e_i \rangle = \\ &= \frac{1}{n(n-1)} \sum_{i,j=1}^n \mathcal{R}(e_j, e_i, e_j, e_i) = \frac{1}{n} \sum_{j=1}^n Ric_p(e_j) \end{aligned}$$

# Ricci and scalar curvature

For  $x, y \in TpM$  consider the linear mapping  $\Phi : \mathcal{X}(M) \rightarrow \mathcal{X}(M)$

$$\Phi(z) = R(x, z)y$$

and define

$$Q(x, y) = \text{tr}(\Phi)$$

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- $Q$  is symmetric. If  $x$  is a unit vector in  $T_p M$ , consider the orthonormal basis  $(e_1, \dots, e_{n-1}, x = e_n)$  of  $T_p M$ . Then, for any  $y \in T_p M$ ,

$$\begin{aligned} Q(x, y) &= \sum_{j=1}^n \langle R(x, e_j)y, e_j \rangle = \\ &= \sum_{j=1}^n \mathcal{R}(x, e_j, y, e_j) = \sum_{j=1}^n \mathcal{R}(y, e_j, x, e_j) = Q(y, x) \end{aligned}$$

In particular, we have

$$Q(x, x) = \sum_{j=1}^n \mathcal{R}(x, e_j, x, e_j) = (n - 1)Ric_p(x)$$

or

$$\frac{1}{n - 1} Q(x, x) = Ric_p(x).$$

Furthermore, there exists a self-adjoint linear operator  $\mu : T_pM \rightarrow T_pM$  such that

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Taking an orthonormal basis  $(e_1, \dots, e_n)$  of  $T_pM$ , we have

$$\operatorname{tr}(\mu) = \sum_{j=1}^n \langle \mu(e_j), e_j \rangle = \sum_{j=1}^n Q(e_j, e_j) = \sum_{j=1}^n (n-1) \operatorname{Ric}_p(e_j) = n(n-1)K(p).$$