

## LECTURE 15: COMPLETENESS

### 1. THE HOPF-RINOW THEOREM

#### ¶ The Hopf-Rinow Theorem and consequences.

Last time we proved that on any compact Riemannian manifold, any nontrivial path-homotopy class contains a shortest curve and that curve must be a geodesic. Today we will study geodesics in a wider class of Riemannian manifolds, namely, complete Riemannian manifolds, and prove the existence of shortest geodesics in each non-trivial path-homotopy class in such manifolds.

We will first prove the existence of shortest geodesics [i.e. a geodesic of length  $d(p, q)$ ] between any two given points  $p, q$  on any complete Riemannian manifold. This is the second part of a well-known theorem proved by Hopf and Rinow in 1931. Recall that a Riemannian manifold  $(M, g)$  is called geodesically complete if the maximal defining interval of any geodesic on  $M$  is  $\mathbb{R}$ . On the other hand, any Riemannian manifold  $(M, g)$  admits a Riemannian metric structure given by

$$d(p, q) = \inf\{L(\gamma) \mid \gamma \text{ is a piecewise smooth curve connecting } p \text{ to } q\},$$

and thus we can talk about the completeness of  $d$ : a metric space is complete if any Cauchy sequence in it converges.

Now we state Hopf-Rinow theorem, which contains two parts: the first part claims that for Riemannian manifolds, the two notions of completeness coincide; while the second part claims the existences of shortest geodesic on such manifolds.

**Theorem 1.1** (Hopf-Rinow). *Let  $(M, g)$  be a connected Riemannian manifold.*

(Part I) *The following statements are equivalent:*

- (1)  *$(M, d)$  is a complete metric space.*
- (2)  *$(M, g)$  is geodesically complete.*
- (3) *There exists  $p \in M$  so that  $\exp_p$  is defined for all  $X_p \in T_p M$ .*
- (4) *[Heine-Borel property] Any bounded closed subset in  $M$  is compact.*

(Part II) *Moreover, each of the previous statements implies*

- (5) *for any  $p, q \in M$ , there exists a geodesic of length  $d(p, q)$  connecting  $p$  and  $q$ .*

**Definition 1.2.** A connected Riemannian manifold  $(M, g)$  satisfying any of (1)-(4) is called a *complete Riemannian manifold*.

*Remark.* Property (5) is NOT enough to guarantee that  $(M, g)$  is complete. For example, the open unit ball  $B_1(0)$  in  $(\mathbb{R}^m, g_0)$  satisfies (5), but is not complete.

*Remark.* For a general metric space, condition (1) does NOT imply condition (4): any infinite dimensional Banach or Hilbert space like  $l^2$  is a counterexample. So as metric spaces, Riemannian manifolds are special (and *nice*) metric spaces.

We list a couple immediate consequences of Hopf-Rinow theorem. Since any compact metric space is complete, we get another proof of

**Corollary 1.3.** *Any compact Riemannian manifold is geodesically complete.*

Since any two points can be connected by a geodesic,

**Corollary 1.4.** *If  $(M, g)$  is complete and connected, then for any  $p \in M$ , the exponential map  $\exp_p : T_p M \rightarrow M$  is surjective.*

Since the Heine-Borel property is inherited by closed subsets, we have [warning: although any closed subspace of a complete metric space is complete, one cannot apply (1) here since “the induced metric on a submanifold  $S$  in the metric space  $(M, d)$ ” is not the same as “the Riemannian distance generated by the induced Riemannian metric on  $S \subset (M, g)$ ”]

**Corollary 1.5.** *Any closed submanifold of a complete Riemannian manifold, when endowed with the induced Riemannian metric, is complete.*

### ¶ Proof of “Hopf-Rinow Theorem, Part II”.

We first prove Part II of Hopf-Rinow theorem. More precisely, we prove  $\boxed{(2) \Rightarrow (5)}$ , or equivalently, its local version, namely  $\boxed{(3) \Rightarrow (5')}$ , where

(5') for any  $q \in M$ , there exists a geodesic of length  $d(p, q)$  connecting  $p$  and  $q$ .

Denote  $r = d(p, q)$ . We have already seen that there exists  $0 < \delta < r$  so that the exponential map  $\exp_p$  is a diffeomorphism from  $B_\delta(0) \in T_p M$  to  $B(p, \delta) \in M$ . Note that the geodesic sphere  $S(p, \delta) = \exp_p(S_\delta(0))$  is compact. Since the distance function is continuous [c.f. lecture 3], there exists  $p_0 \in S(p, \delta)$  so that

$$d(p_0, q) = \inf_{p' \in S(p, \delta)} d(p', q).$$

Let  $\gamma$  be the normal geodesic from  $p$  to  $p_0$ . By (3),  $\gamma$  is defined over  $\mathbb{R}$ . Let

$$A = \{s \in [\delta, r] \mid d(\gamma(s), q) = r - s\}.$$

We will show  $\sup A = r$ , which implies  $\gamma(r) = q$ .

To prove this, we first notice that  $\delta \in A$ , since

$$r = d(p, q) = \inf_{p' \in S(p, \delta)} (d(p, p') + d(p', q)) = \delta + \inf_{p' \in S(p, \delta)} d(p', q) = \delta + d(\gamma(\delta), q).$$

So  $A$  is nonempty.

Secondly, it's easy to see that  $A$  is closed, since the function

$$f(s) = d(\gamma(s), q) - r + s$$

is continuous and  $A = f^{-1}(0) \cap [\delta, r]$ .

Now let  $s_0 = \sup A$ . Since  $A$  is nonempty and closed,  $s_0 \in A$ . Suppose  $s_0 < r$ . Then by repeating the previous argument, we know that there exists  $0 < \delta' < r - s_0$  and  $p'_0 \in S(\gamma(s_0), \delta')$  so that

$$d(p'_0, q) = \min_{p' \in S(\gamma(s_0), \delta')} d(p', q) = d(\gamma(s_0), q) - \delta'.$$

Since  $s_0 \in A$ , we get

$$d(p'_0, q) = r - s_0 - \delta'.$$

So by the triangle inequality,

$$d(p'_0, p) \geq d(p, q) - d(p'_0, q) = r - (r - s_0 - \delta') = s_0 + \delta'.$$

On the other hand, the curve  $\tilde{\gamma}$  by connecting  $p$  to  $\gamma(s_0)$  along  $\gamma$  and then connecting  $\gamma(s_0)$  to  $p'_0$  by the “radial” minimal geodesic has length exactly  $s_0 + \delta'$ . So  $\tilde{\gamma}$ , with the arc-length parametrization, must be a geodesic. Obviously  $\tilde{\gamma}$  has to coincide with  $\gamma$ . In other words,  $p'_0 = \gamma(s_0 + \delta')$ . As a consequence,

$$d(\gamma(s_0 + \delta'), q) = r - (s_0 + \delta'),$$

i.e.  $s_0 + \delta' \in A$ . This conflicts with the fact that  $s_0 = \sup A$ .

### ¶ Proof of “Hopf-Rinow Theorem, Part I”.

Having proved (3)  $\implies$  (5'), now we prove part I of Hopf-Rinow's theorem by

$$(4) \implies (1) \implies (2) \implies (3) \quad \text{and} \quad (3) + (5') \implies (4).$$

**(4) $\implies$ (1)** This is a standard result in general topology: Let  $p_i$  be any Cauchy sequence, then the set  $\{p_i\}$  is contained in bounded ball  $B$  whose closure is compact by (4). It follows that  $p_i$  has a subsequence that converges to some  $p_0$ . But  $p_i$  is a Cauchy sequence, so the entire sequence  $p_i \rightarrow p_0$ .

**(1) $\implies$ (2)** Let  $\gamma$  be any normal geodesic on  $M$ . By the existence and uniqueness theorem, the maximal defining interval of  $\gamma$  must be an open interval  $(a, b)$ . If  $b < \infty$ , then we can take a sequence  $s_i \rightarrow b-$ . In particular,  $s_i$  is a Cauchy sequence in  $\mathbb{R}$ . But  $\gamma$  is a normal geodesic, so

$$d(\gamma(s_i), \gamma(s_j)) \leq |s_i - s_j|.$$

As a consequence,  $\gamma(s_i)$  is a Cauchy sequence in  $(M, d)$ . It follows that there exists a point  $p \in M$  so that  $\gamma(s_i) \rightarrow p$ .

Since  $\mathcal{E}$  is open and  $(p, 0) \in \mathcal{E}$ , there exists  $\varepsilon > 0$  so that  $(q, Y_q) \in \mathcal{E}$  for any  $q$  with  $d(q, p) < \varepsilon$  and any  $Y_q \in T_q M$  with  $|Y_q| < 2\varepsilon$ . So if we take  $i$  large enough so that  $b - s_i < \frac{\varepsilon}{2}$  and thus  $d(\gamma(s_i), p) < \frac{\varepsilon}{2}$ , then  $\gamma(t; \gamma(s_i), \varepsilon \dot{\gamma}(s_i))$  is defined for  $t \in [0, 1]$ . In other words, the geodesic  $\gamma_1(t) = \gamma(t; \gamma(s_i), \dot{\gamma}(s_i))$  is well defined for  $0 < t < \varepsilon$ . Since  $\gamma_1$  coincides with  $\gamma$  at  $s_i$ , they must be the same. In particular,  $\gamma$  can be defined for all  $t < s_i + \frac{\varepsilon}{2}$ , which exceeds the upper bound  $b$ , a contradiction.

Similarly by considering the “reverse geodesic” one also has  $a = -\infty$ . So any normal geodesic on  $M$ , and thus any geodesic on  $M$ , has defining interval  $\mathbb{R}$ .

$\boxed{(2)\Rightarrow(3)}$  This is obvious. ( $(M, g)$  is geodesically complete  $\Leftrightarrow \mathcal{E} = TM$ .)

$\boxed{(3)+(5')\Rightarrow(4)}$  Let  $K \subset M$  be a bounded closed set. Then there exists a constant  $C > 0$  so that  $d(p, k) < C$  for all  $k \in K$ . According to (3) and (5'),  $K \subset \exp_p(\overline{B_C(0)})$ , where  $\overline{B_C(0)}$  is the *closed* ball of radius  $C$  in  $T_pM$ , which is compact in  $T_pM$ . Since  $\exp_p$  is smooth,  $\exp_p(\overline{B_C(0)})$  is also compact. Thus  $K$ , as a closed subset of a compact set, is compact.

## 2. GEODESICS AND RIEMANN COVERING MAP

### ¶ Lifting to the Riemannian covering.

Next let's turn to prove the existence of length minimizing geodesics in any path-homotopy class of curves connecting  $p$  to  $q$ . The idea is to straightforward: instead of working on piecewise smooth curves in  $M$  connecting given points  $p$  and  $q$  that lies in a given path-homotopy classes, we will move to the universal covering  $\pi : \widetilde{M} \rightarrow M$  of  $M$  and work on piecewise smooth curves starting with a fixed  $\tilde{p} \in \pi^{-1}(p)$  and ends at the point  $\tilde{q} \in \pi^{-1}(q)$  so that any curve connecting  $\tilde{p}$  and  $\tilde{q}$  projects to a curve in the given path-homotopy classes, and then we can apply the second part of Hopf-Rinow theorem.

For the argument mentioned above to work, we need a couple ingredients. First, we need to lift the complete metric  $g$  on  $M$  to a complete metric on its universal covering  $\widetilde{M}$ . Recall

- Let  $M, N$  be connected smooth manifolds. A smooth map  $f : M \rightarrow N$  is said to be a *smooth covering map* if
  - (1) for any  $q \in N$ , there is a neighborhood  $V$  of  $q$  in  $N$  and open subsets  $U_\alpha$  of  $M$  so that  $f^{-1}(V) = \cup_\alpha U_\alpha$ ,
  - (2) for each  $\alpha$ ,  $f : U_\alpha \rightarrow V$  is a diffeomorphism,
  - (3) these  $U_\alpha$ 's are disjoint.

As is well known, if  $f : M \rightarrow N$  is a covering map, then

- $\dim M = \dim N$  and  $f$  is surjective,
- fix any  $p_\alpha \in f^{-1}(q)$ , any path (and path homotopy) starts at  $q$  in  $N$  admits a unique lifting to  $M$  that starts at  $p_\alpha$ ,
- moreover, if  $N$  is simply connected, then  $f$  is a global diffeomorphism.
- If  $(M, g_M)$  and  $(N, g_N)$  are Riemannian manifolds, then a smooth covering map  $\pi : M \rightarrow N$  is called a *Riemannian covering map* if  $\pi^*g_N = g_M$ . Note:
  - given any smooth covering map  $\pi : M \rightarrow N$  and any Riemannian metric on  $N$ , one may pullback that metric to  $M$  to make the covering map a Riemannian covering. [c.f. PSet 1 Problem 3]
  - any Riemannian covering map is a local isometry.
- We also need some standard properties of local isometries. Let  $f : (M, g) \rightarrow (N, h)$  be a local isometry, then

- $M$  and  $N$  have “the same” Riemannian metrics at corresponding points, and thus the same Levi-Civita connection and the same Riemannian curvature at corresponding points [c.f. PSet 2 Problem 1].
- In particular,  $f$  maps geodesics into geodesics, and if  $f$  is a Riemannian covering, then the lifting of a geodesic is a geodesic.
- for any piecewise smooth curve  $\gamma$  in  $M$ , one has  $|\dot{\gamma}|_{\gamma(t)} = |df_{\gamma(t)}(\dot{\gamma})|_{f(\gamma(t))}$  and thus  $L(\gamma) = L(f(\gamma))$ .

Now we prove

**Proposition 2.1.** *Let  $(M, g)$  be a complete Riemannian manifold, and  $\pi : \widetilde{M} \rightarrow M$  be a smooth covering map. Then  $(\widetilde{M}, \pi^*g)$  is complete.*

*Proof.* For any  $\tilde{p} \in \widetilde{M}$  and any  $\tilde{v} \in T_{\tilde{p}}\widetilde{M}$ , we denote  $p = \pi(\tilde{p})$  and  $v = d\pi_{\tilde{p}}(\tilde{v})$ . Then by definition of completeness, there is a geodesic  $\gamma : \mathbb{R} \rightarrow M$  with  $\gamma(0) = p$  and  $\dot{\gamma}(0) = v$ . By the path-lifting property for covering space, there is a unique lifting  $\tilde{\gamma} : \mathbb{R} \rightarrow \widetilde{M}$  with  $\tilde{\gamma}(0) = \tilde{p}$ , which is a geodesic since it is the lifting of a geodesic.. Moreover, since  $\pi : (\widetilde{M}, \pi^*g) \rightarrow (M, g)$  is a local isometry and since  $\pi \circ \tilde{\gamma} = \gamma$ , we get

$$\dot{\tilde{\gamma}}(0) = (d\pi_{\tilde{p}})^{-1}(\dot{\gamma}(0)) = (d\pi_{\tilde{p}})^{-1}(v) = \tilde{v}.$$

So the geodesic starts at  $\tilde{p}$  in the direction  $\tilde{v}$  is defined over  $\mathbb{R}$ . □

### ¶ Length minimizing curves in given path-homotopy class.

As a consequence, we can extend Theorem 1.4 in Lecture 14 to complete Riemannian manifolds.

**Theorem 2.2.** *Let  $(M, g)$  be a complete connected Riemannian manifold, and  $p, q$  are two points in  $M$ . Then in each path-homotopy class of curves  $\gamma$  with  $\gamma(0) = p, \gamma(1) = q$ , there is a length-minimizing piecewise smooth curve and it is a geodesic.*

*Proof.* Consider the universal covering  $\pi : \widetilde{M} \rightarrow M$ . Equip  $\widetilde{M}$  with the covering Riemannian metric  $\pi^*g$ . Given any path  $\sigma : [0, 1] \rightarrow M$  connecting  $p$  and  $q$  in the given homotopy class, and given any  $\tilde{p} \in \pi^{-1}(p)$ , there is a unique lifting  $\tilde{\sigma} : [0, 1] \rightarrow \widetilde{M}$  of  $\sigma$  with  $\tilde{\sigma}(0) = \tilde{p}$ . Since  $(\widetilde{M}, \pi^*g)$  is complete, by Hopf-Rinow theorem, there is a minimizing geodesic  $\tilde{\gamma}$  from  $\tilde{p}$  to  $\tilde{q} := \tilde{\sigma}(1)$ . Since  $\pi$  is a local isometry, the projection  $\gamma = \pi \circ \tilde{\gamma}$  is a geodesic in  $M$  with  $\gamma(0) = p, \gamma(1) = q$ . Since  $\widetilde{M}$  is simply connected,  $\tilde{\gamma}$  is path-homotopic to  $\tilde{\sigma}$  and thus  $\gamma$  is path-homotopic to  $\sigma$ .

Finally suppose  $\sigma_1$  be any piecewise smooth curve in  $M$  from  $p$  to  $q$  in the given path homotopy class, then its lifting  $\tilde{\sigma}_1$  in  $\widetilde{M}$  with starting point  $\tilde{\sigma}_1(0) = \tilde{p}$  must ends at  $\tilde{q}$ , and thus by our choice of  $\tilde{\gamma}$ ,

$$L(\gamma) = \text{Length}(\tilde{\gamma}) \leq \text{Length}(\tilde{\sigma}_1) = L(\sigma_1).$$

So  $\gamma$  is the shortest curve in the given path homotopy class. □