#### SEISMOLOGY I

Laurea Magistralis in Physics of the Earth and of the Environment

## Seismic Surface waves

Fabio ROMANELLI Dept. Earth Sciences Università degli studi di Trieste <u>romanel@dst.units.it</u>

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Surface waves in an elastic half spaces: Rayleigh waves

- Potentials
- Free surface boundary conditions
- Solutions propagating along the surface, decaying with depth
- Lamb's problem

#### Surface waves in media with depth-dependent properties: Love waves

- Constructive interference in a low-velocity layer
- Dispersion curves
- Phase and Group velocity

**Free Oscillations** 

- Spherical Harmonics
- Modes of the Earth
- Rotational Splitting



## Data Example





#### Question:

We derived that Rayleigh waves are non-dispersive!

But in the observed seismograms we clearly see a highly dispersed surface wave train?

We also see dispersive wave motion on both horizontal components!

Do SH-type surface waves exist? Why are the observed waves dispersive?





In an elastic half-space no SH type surface waves exist. Why? Because there is total reflection and no interaction between an evanescent P wave and a phase shifted SV wave as in the case of Rayleigh waves. What happens if we have a layer over a half space (Love, 1911)?



Repeated reflection in a layer over a half space.

Interference between incident, reflected and transmitted SH waves.

When the layer velocity is smaller than the halfspace velocity, then there is a critical angle beyond which SH reverberations will be totally trapped.



Love waves: trapping - 1





$$u_{y1} = A \exp[i(\omega t + kr_{\beta 1}z - kx)] + B \exp[i(\omega t - kr_{\beta 1}z - kx)]$$

$$\mathbf{u}_{y2} = C \exp[i(\omega t - kr_{\beta 2}z - kx)]$$





The formal derivation is very similar to the derivation of the Rayleigh waves. The conditions to be fulfilled are:

- 1. Free surface condition
- 2. Continuity of stress on the boundary
- 3. Continuity of displacement on the boundary
- 4. No radiation in the halfspace

1. 
$$\sigma_{zy1}(0) = \mu_1 \frac{\partial u_{y1}}{\partial z} \bigg|_0 = ikr_{\beta 1} \Big\{ Aexp[i(\omega t - kx)] - Bexp[i(\omega t - kx)] \Big\} = 0$$

2. 
$$\sigma_{zy1}(H) = \mu_1 \frac{\partial u_{y1}}{\partial z}\Big|_{H} = \sigma_{zy2}(H) = \mu_2 \frac{\partial u_{y2}}{\partial z}\Big|_{H}$$
 3.  $u_{y1}(H) = u_{y2}(H)$ 

4. 
$$\lim_{\infty} u_{y^2}(z) = 0$$
 i.e.  $c < \beta_2$  i.e.  $r_{\beta^2} = -i \sqrt{1 - \frac{c^2}{\beta_2^2}}$ 





We obtain a condition for which solutions exist. This time we obtain a frequency-dependent solution a dispersion relation

$$\tan(H\omega\sqrt{1/\beta_1^2 - 1/c^2}) = \frac{\mu_2\sqrt{1/c^2 - 1/\beta_2^2}}{\mu_1\sqrt{1/\beta_1^2 - 1/c^2}}$$

... indicating that there are only solutions if ...

$$\beta_1 < C < \beta_2$$



## Love Waves: Solutions



Graphical solution of the previous equation. Intersection of dashed and solid lines yield discrete **modes**.

$$\tan(H\omega\sqrt{1/\beta_1^2} - 1/c^2) = \tan(\omega\xi)$$

that vanishes when  $\zeta = n \frac{\pi}{\omega}$ 

New modes appear at cut-off frequencies















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Graphical solution of the previous equation. Intersection of dashed and solid lines yield solutions while frequency is varying: discrete modes.

Every mode is characterized by a dispersion curve  $(c=c(\omega))$ , showing the solution to the eigenvalue problem.

For every value of c one can b calculate the **eigenfunction**, i.e. the displacement ,  $u_v$ , versus depth.







#### Love Waves: modes



Some modes for Love waves





## Love Waves: modes











The conditions to be fulfilled are:

- 1. Free surface condition
- 2. No S-wave potential and shear stress in the liquid layer
- 3. Continuity of stress at the liquid-layer interface
- 4. Continuity of vertical component of displacement at the liquid layer interface (horizontal is free due to no viscosity in perfect liquid)

$$\tan(H\omega\sqrt{1/\alpha_w^2 - 1/c^2}) = \frac{\rho\beta^4\sqrt{c^2/\alpha_w^2 - 1}}{\rho_w c^4\sqrt{1 - c^2/\alpha^2}}$$
$$\left[-(2 - c^2/\beta^2)^2 + 4(1 - c^2/\alpha^2)^{1/2}(1 - c^2/\beta^2)^{1/2}\right]$$



Similar derivation for Rayleigh type motion leads to dispersive behavior





## Wavefields visualization



#### P Wave



#### **Rayleigh Wave**



Love Wave

















Interference of two waves at two positions (1)









Interference of two waves at two positions (2)

$$x = 1.5 \text{ km}$$

$$x = 1.5 \text{ km}$$

$$x = 1.5 \text{ km}$$

$$A' + B'$$

$$U = \frac{1.5 \text{ km}}{0.5 \text{ sec}} = 3 \text{ km/sec}$$

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The typical dispersive behavior of surface waves solid - group velocities; dashed - phase velocities







Demonstration: sum two harmonic waves with slightly different angular frequencies and wavenumbers:

$$u(x, t) = \cos(\omega_1 t - k_1 x) + \cos(\omega_2 t - k_2 x)$$

$$\omega_1 = \omega + \delta \omega \qquad \omega_2 = \omega - \delta \omega \qquad \omega \gg \delta \omega$$
$$k_1 = k + \delta k \qquad k_2 = k - \delta k \qquad k \gg \delta k$$

Add the two cosines:

$$u(x, t) = \cos(\omega t + \delta \omega t - kx - \delta kx)$$
$$+ \cos(\omega t - \delta \omega t - kx + \delta kx)$$
$$= 2\cos(\omega t - kx)\cos(\delta \omega t - \delta kx)$$

The envelope (beat) has a group velocity:

 $U=\delta\omega/\delta k$ 

The individual peaks move with a *phase velocity*:  $c = \omega/k$ 





#### Fourier domain

Fourier transform:  $F(\omega) = \int f(t)e^{-i\omega t} dt$ 

Inverse Fourier transform:  $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{i\omega t} d\omega$ 

 $F(\omega) = A(\omega)e^{i\phi(\omega)}$ 

with a magnitude,  $A(\omega) = |F(\omega)|$ , and phase,  $\phi(\omega)$ .

So the Fourier transform represents a time series by two real functions of angular frequency: the *amplitude* spectrum,  $A(\omega)$ , and the *phase spectrum*,  $\phi(\omega)$ .

The displacements are:  $u(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) \exp i[\omega t - k(\omega)x + \phi_i(\omega)] d\omega$ 

The phase has two parts (propagation and initial phase):  $\Phi(\omega) = \omega t - k(\omega)x + \phi_i(\omega)$ 

The phase velocity  $c(\omega) = \omega/k(\omega)$  describes wave surfaces of constant phase (individual peaks).





To find the group velocity of energy propagation in the angular frequency band between  $\omega_0 - \Delta \omega$  and  $\omega_0 + \Delta \omega$ , first approximate the wavenumber  $k(\omega)$  by the first term of a Taylor series about  $\omega_0$ :

$$k(\omega) \approx k(\omega_0) + \frac{dk}{d\omega} \Big|_{\omega_0} (\omega - \omega_0)$$

This gives: 
$$u(x, t) \approx \frac{1}{2\pi} \int_{\omega_0 - \Delta\omega}^{\omega_0 + \Delta\omega} A(\omega) \exp\left[i\left(\omega t - k(\omega_0)x - \frac{dk}{d\omega}\Big|_{\omega_0}(\omega - \omega_0)x + \phi_i(\omega)\right)\right] d\omega$$

$$u(x,t) \approx \frac{1}{2\pi} \int_{\omega_0 - \Delta\omega}^{\omega_0 + \Delta\omega} A(\omega) \exp\left[i\left((\omega - \omega_0)(t - \frac{dk}{d\omega}\Big|_{\omega_0} x) + (\omega_0 t - k(\omega_0)x) + \phi_i(\omega)\right)\right] d\omega$$

Compare to the simple situation of two cosine waves:

$$u(x, t) = 2\cos(\omega t - kx)\cos(\delta\omega t - \delta kx)$$

Similar to the cosine waves, the group velocity is defined as  $U(\omega) = \frac{d\omega}{dk}$ 













Fundamental Mode Rayleigh dispersion curve for a layer over a half space.





## Dispersion...



The group velocity itself is usually a function of the wave's frequency. This results in group velocity dispersion (GVD), that is often quantified as the group delay dispersion parameter : If D is < 0, the medium is said to have **positive dispersion**. If D is > 0, the medium has **negative dispersion**.

$$\mathsf{D} = \frac{\mathsf{d}\mathsf{v}_g}{\mathsf{d}\omega}$$



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Airy Phase -

wave that arises if the phase and the change in group velocity are stationary and gives the highest amplitude in terms of group velocity and are prominent on the seismogram.









Stronger gradients cause greater dispersion



## Wave Packets



Seismograms of a Love wave train filtered with different central periods. Each narrowband trace has the appearance of a wave packet arriving at different times.











Figure 1.2.1b Composite of dispersion curves for surface waves.





## One station method

- 1. Directly measure the arrival time of the peaks and troughs on one seismogram
- Narrow filtered the seismogram, measure the arrival of the peak of the wave packet (more accurate)

$$U(\omega) = \frac{x}{t}$$
 Need know the origin time and the location of the earthquake source





#### Determination of group velocities at one station







#### Two stations method

If two stations are located on the same great circle path, group velocity can be obtained by measuring the difference in arrival times of filtered wave packets.













#### Figure 2.8-5: Rayleigh wave group velocity study of the Walvis ridge.





Directly measured at two stations







# Measured by taking Fourier transform and obtaining phase spectrum

A surface wave can be represented:

$$u(x,t) = \frac{1}{\pi} \int_{0}^{\infty} A(\omega, x) \cos(\omega t - \frac{\omega}{c(\omega)} x + \phi_0(x)) d\omega$$

$$\phi(\omega) = \omega t - \frac{\omega}{c(\omega)} x + \phi_0(\omega) + 2\pi N$$





#### **One-station method**

$$\phi_1(\omega) = \omega t_1 - \frac{\omega}{c(\omega)} x_1 + \phi_0(\omega) + 2\pi N$$





#### One-station method

$$\phi_1(\omega) = \omega t_1 - \frac{\omega}{c(\omega)} x_1 + \phi_0(\omega) + 2\pi N$$

## Need know the initial phase $\varphi_0$

N can be determined by by allowing c(w) for the longest period converge to the global average





Figure 2.8-6: Example of Rayleigh wave phase velocities for ocean lithosphere.

On a seismogram recorded at a distance x from the earthquake at time t after the earthquake, the phase has three terms:

 $\Phi(\omega) = [\omega t - k(\omega)x] + \phi_i(\omega) + 2n\pi$ 

 $= [\omega t - \omega x/c(\omega)] + \phi_i(\omega) + 2n\pi$ 

 $\omega t - k(\omega)x$  is the phase due to the propagation of the wave in time and space.

 $\phi_i(\omega)$  includes the initial phase at the earthquake and any phase shift introduced by the seismometer.

 $2n\pi$  reflects the periodicity of the complex exponential, because adding an integral multiple of  $2\pi$  to the argument yields the same value.







Figure 2.8-6: Example of Rayleigh wave phase velocities for ocean lithosphere.

Two station method:

 $\Phi_1(\omega) = \omega t_1 - \omega x_1/c(\omega) + \phi_i(\omega) + 2n\pi$ 

 $\Phi_2(\omega) = \omega t_2 - \omega x_2/c(\omega) + \phi_i(\omega) + 2m\pi$ 

Take the difference  $\Phi_{21} = \Phi_2 - \Phi_1$ , and solve for c:

$$c(\omega) = \omega(x_2 - x_1) / [\omega(t_2 - t_1) + 2(m - n)\pi - \Phi_{21}(\omega)].$$

The  $2(m - n)\pi$  term is found empirically by ensuring that the phase velocity at long periods is reasonable.

Single station method:

Predict the phase at the earthquake from its focal mechanism. If  $\phi_i(\omega)$  is known, c is:

$$c(\omega) = \omega x / [\omega t + \phi_i(\omega) + 2n\pi - \Phi(\omega)]$$

![](_page_41_Figure_13.jpeg)

![](_page_42_Picture_0.jpeg)

![](_page_42_Picture_1.jpeg)

#### Figure 2.8-7: Rayleigh wave phase velocity dispersion as a function of oceanic plate age.

![](_page_42_Figure_3.jpeg)